

Dynamics in Games

A particular dynamics is a behavioural model for players, i.e., how they should play over time.
 i.e., For $t \in [0, \infty)$, dynamics specifies the strategy $x(t), y(t)$ played by the two players.

I ideally, would like:

- (i) the dynamics should "converge" quickly to a stable state
- (ii) the players should not require excessive information (eg, other player's payoff) to follow the dynamics
- (iii) player actions should be "natural": not play obviously bad strategies, not solve computationally hard problems
- (iv) ideally, players should play pure strategies in each round, i.e., $x(t) = e_i$ for $i \in [n]$

Dynamics also referred to as learning in games, since players "learn" stable strategies.

E.g., a bad dynamic would be that one player knows all payoffs, computes a MNE σ , & tells all other players to play according to σ ...

2-Player Game: Fictitious Play

Let x, y be the two players. S_x, S_y be the pure strategies. In FP, at each time step, each player plays a pure strategy $x(t), y(t)$. Think of each as a vector in $\Delta_{|S|}$. Define $\bar{x}(t) = \frac{1}{t+1} \sum_{\tau=0}^t x(\tau)$. This is a mixed strategy for both players, or the empirical distribution of pure strategies played until time t .

Fictitious Play:

- in round zero, each player picks an arbitrary pure strategy & plays it. $x(0) \in S_x, y(0) \in S_y$.
 (technically, $x(0) = e_i$ for some $i \in [S_x]$, $y(0) = e_j$ for some $j \in [S_y]$)
- in round t , each player picks a pure best-response to the empirical distribution of pure strategies played until round $t-1$

$$x(t) \in \arg \max_{s_x \in S_x} u_x(s_x, \bar{y}(t-1))$$

$$y(t) \in \arg \max_{s_y \in S_y} u_y(s_y, \bar{x}(t-1))$$

How does this do on our list of desiderata?

- ? not sure if it converges, or to what
- + players only need to know their own payoffs & what others have played
- + easy to compute, no coordination required
- + pure strategies

An Example:

	L	R
U	3 \ 3	0 \ 0
D	4 \ 0	1 \ 1

(D, R) obtained by IEDS, hence only NE.

	$x(t)$	$y(t)$	$\bar{x}(t)$	$\bar{y}(t)$
Say $x(0) = U, y(0) = L$	$t=0$	U	L	(1,0) (1,0)
	$t=1$	D	L	(1/2, 1/2) (1,0)
	$t=2$	D	L	(2/3, 2/3) (1,0)
	$t=3$	D	L	(3/4, 3/4) (1,0)
	$t=4$	D	L	(4/5, 4/5) (1,0)
	$t=5$	D	R	(5/6, 5/6) (5/6, 5/6)
	$t=6$	D	R	(6/7, 6/7) (6/7, 6/7)
	...			

In this case, FP seems to converge to a pure NE.

Example 2:

	L	R
U	0 \ 0	1 \ 1
D	1 \ 1	0 \ 0

Note that game has 2 pure NE & 1 mixed NE

	$x(t)$	$y(t)$	$\bar{x}(t)$	$\bar{y}(t)$
Say $x(0) = U, y(0) = L$	$t=0$	U	L	(1,0) (1,0)
	$t=1$	D	R	(1/2, 1/2) (1/2, 1/2)
	$t=2$	D	R	(2/3, 2/3) (2/3, 2/3)
	$t=3$	U	L	(2/3, 1/3) (1/3, 2/3)
	$t=4$	U	L	(3/4, 1/4) (1/4, 3/4)
	$t=5$	D	R	(5/6, 1/6) (1/6, 5/6)
	...			

so, doesn't converge to a pure NE in this case.

Defn A sequence of pure strategies $(x(t), y(t))$ converges to (x^*, y^*) if $\exists T : \forall t \geq T, x(t) = x^*, y(t) = y^*$

(thus for each coordinate $i, \lim_{t \rightarrow \infty} \bar{x}_i(t) \rightarrow x_i^*$
 $\lim_{t \rightarrow \infty} \bar{y}_j(t) \rightarrow y_j^*$)

OR, if $(x(t), y(t))$ converges to (x^*, y^*) , then $(\bar{x}(t), \bar{y}(t))$ converges to (x^*, y^*) in the typical sense

$$\forall \epsilon \exists T : \forall t \geq T, \|y^* - \bar{y}(t)\|_\infty \leq \epsilon \quad \forall t \geq T$$

Thus, if $(x(t), y(t))$ converges to (x^*, y^*) , then

$$\forall \epsilon \exists T \forall t \geq T, \|Ry^* - R\bar{y}(t)\|_\infty \leq \epsilon$$

$$\forall \epsilon \exists T \forall t \geq T, \|Cx^* - C\bar{x}(t)\|_\infty \leq \epsilon$$

Lemma (i) If the sequence of pure strategies $(x(t), y(t))$ in FP converges to (x^*, y^*) , then (x^*, y^*) is a PNE

(ii) If (x^*, y^*) is a strict PNE, and $\exists t : (x(t), y(t)) = (x^*, y^*)$, then $(x(\tau), y(\tau)) = (x^*, y^*) \quad \forall \tau \geq t$

Proof (i) Assume for contradiction $(x(t), y(t)) \rightarrow (x^*, y^*)$ but (x^*, y^*) is not NE. $\exists i, j : x_j^* > 0, (Ry^*)_i > (Ry^*)_j = \epsilon > 0$

- we know that $\exists T_0$ s.t. $\forall t \geq T_0, \|Ry^* - R\bar{y}(t)\|_\infty < \epsilon/4$
 $\Rightarrow |(Ry^*)_i - (R\bar{y}(t))_i| < \epsilon/4$
 and $|(Ry^*)_j - (R\bar{y}(t))_j| < \epsilon/4$

it follows that $(R\bar{y}(t))_i - (R\bar{y}(t))_j \geq \epsilon/2 \quad \forall t \geq T_0$
 but this is a contradiction, since if $(R\bar{y}(t))_i > (R\bar{y}(t))_j$, $x_j(t+1) = 0 \quad \forall t \geq T_0$. But $x(t) \rightarrow x^*$, and $x_j^* > 0$ by assumption.

(ii) $x(t) = x^*, y(t) = y^*$
 Thus $x^* R \bar{y}(t-1) \geq \hat{x} R \bar{y}(t-1) \quad \forall \hat{x} \in S_x$
 $x^* R y^* > \hat{x} R y^* \quad \forall \hat{x} \in S_x \setminus x^*$
 $\Rightarrow x^* R \bar{y}(t) > \hat{x} R \bar{y}(t) \quad \forall \hat{x} \in S_x \setminus x^*$
 Hence, $x(t+1) = x^*, y(t+1) = y^*$

Lemma If the sequence $(\bar{x}(t), \bar{y}(t))$ converges to (x^*, y^*) , then (x^*, y^*) is a MNE.

Proof Say (x^*, y^*) is not MNE. Then $\exists i, j \in [m] : x_j^* > 0$ but $(Ry^*)_i > (Ry^*)_j$.
 Say $\epsilon = (Ry^*)_i - (Ry^*)_j > 0$
 $\exists T : \forall t \geq T, \|Ry^* - R\bar{y}(t)\|_\infty \leq \epsilon/4$
 $\Rightarrow \|(Ry^*)_i - (R\bar{y}(t))_i\| \leq \epsilon/4$
 & $|(Ry^*)_j - (R\bar{y}(t))_j| \leq \epsilon/4$
 Thus, $(R\bar{y}(t))_i - (R\bar{y}(t))_j \geq \epsilon/2$
 But then $\forall t \geq T, x_j(t) = 0$
 This contradicts that $\bar{x}(t) \rightarrow x^*$, since $x_j^* > 0$.

Theorem FP converges under the following conditions:

- (i) G is a 2-player 0-sum game
- (ii) G is solvable under strict IEDS
- (iii) G is an exact potential game.

Coarse- Correlated Equilibrium

So far, we've thought of a MNE $\sigma = (\sigma_1, \sigma_2, \dots, \sigma_n)$ as a tuple of mixed strategies.

This defines a distribution over pure strategy profiles:

$$\sigma = (\sigma(s_1, \dots, s_n)) = \prod_{i=1}^n \sigma_i(s_i)$$

Thus, σ is a product distribution over pure strategy profiles. Since it is a product distribution, the players pick their strategies from their individual distributions, w/o coordinating with other players.

Suppose however we consider distributions over S that are not product distributions.

So now, $\sigma \in \Delta_{|S|}$ is a distribution over all pure strategies.

$$\forall i, t_i \in S_i, \sigma(t_i) = \sum_{s_{-i}: s_{-i} = t_{-i}} \sigma(s)$$

$$\forall i, t_i \in S_i, \sigma(t_{-i}) = \sum_{s_i: s_i = t_i} \sigma(s) = \sum_{s \in S} \sigma(s)$$

Example: Traffic Game

	S	G
S	0 \ 0	0 \ 10
G	10 \ 0	-10 \ -10

3 equilibria: (S,G), (G,S) and MNE $(\frac{10}{11}, \frac{1}{11})$

Realistically, one would expect one player to stop half the time, & the other player to stop the other half.

So, a good distribution would be: $\sigma(S,G) = 1/2, \sigma(G,S) = 1/2$.

This is obviously not possible as a MNE.

Defn $\sigma \in \Delta_{|S|}$ is a Coarse Correlated Equilibrium (CCE), aka a Harsanyi Equilibrium, if $\forall i, \forall \hat{s}_i \in S_i$,

$$u_i(\sigma) \geq \sum_{s \in S} u_i(\hat{s}_i, s_{-i}) \cdot \sigma(s) = \sum_{s_i \in S_i} \sigma(s_i) u_i(\hat{s}_i, s_{-i})$$

One interpretation is that, given σ , my utility for playing according to σ is at least as much as if I played a pure strategy, and others according to the distribution.

However, in a product distribution, each player independently chooses a pure strategy, which determines the distribution. If distribution is not a product distribution, how do we achieve this? This seems to assume some correlation among the players.

Recall the traffic game. In real-life, we do have a correlating device: a traffic signal.

Thus, a CCE σ corresponds to the following

- a distribution σ over S is fixed and known to all.
- a correlating device picks a pure strategy s from this distribution

- without knowing s , each agent i chooses either to:
 - (i) play a pure strategy s_i , or
 - (ii) learn s_i & play it.

If σ is a CCE, each player chooses the second option.

Note every MNE is a CCE.

Finally, a CCE can be easily computed in polytime:

Let σ_s be a variable for all $s \in S$.

$$\text{Then } \forall i, \forall \hat{s}_i, \sum_{s \in S} u_i(s) \sigma_s \geq \sum_{s \in S} u_i(\hat{s}_i, s_{-i}) \sigma_s$$

$$\forall s \in S, \sigma_s \geq 0$$

$$\sum_s \sigma_s = 1$$